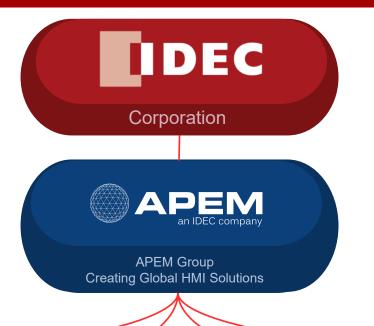




Introducing custom mobile robotics with ez-wheel and ez-way

Organization structure









Components: panel switches, PCB switches (including MEC), LED indicators, industrial switches



Joysticks: from thumb and finger operation to full hand grip products



Panel Solutions: from standard solutions to complete HMIs

PRODUCT OFFERING

Market-Segments IDEC

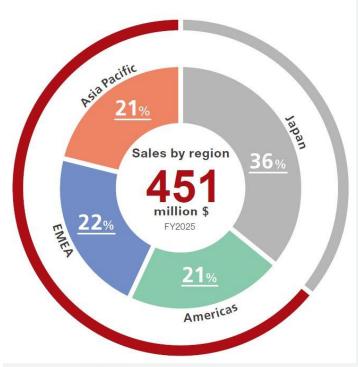


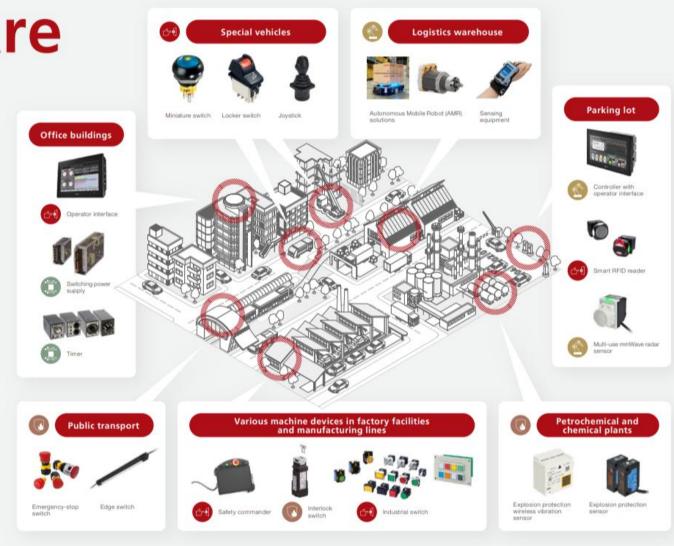
Who We Are

Countries and regions

64_% 16

Ratio of overseas sales





Products APEM





APEM has the capability to design and manufacture specific switch panels and joysticks with its expertise in numerous technologies and communication protocols.



IG series – momentary pushbutton with late-stage customization.



Dualmec 6C series is the smallest two-pole SMD tactile switch on the market.



HR series with an infinite scrolling wheel is the new way to integrate encoders in grips and control panels.





Dual Icon Indicator – two distinct visual signals in one single unit.



PK range - compact, modular and CANbus keypads.



Roadmap overview







World's first self-propelled wheel, 2010



Series 300 / 10"

First product, integrated and versatile Discontinued in 2026



Series 160

Focus on assisted manual handling *Trolleys, medical devices, logistics carts*



Series 150

Heavy load wheel drive Industrial tools

+ performance ++ modularity +++ safety





World's first safety wheel drive, 2021



SWD® Core / 125

Gearmotor range with full safety Robots, pallet shuttles, lifts, conveyors



SWD® 150 / 200

"Safety Wheel Drive"

Mobile robotics, AGVs, AMRs



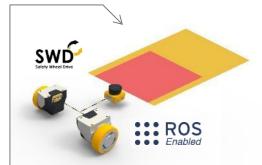
SWD® Starter Kit

Safety + ROS development kit

Mobile robotics

From **ez-Wheel**® to **ez-Way**® => creating value by encapsulating advanced software into smart embedded systems

+ embedded IT ++ connectivity +++ navigation





Paving the way to a safety certified **mobile robotics platform** supporting open-source software, 2025-2030



Navigation & FMS suite

Local operating software for AGVs, AMRs Fleet management system and APIs

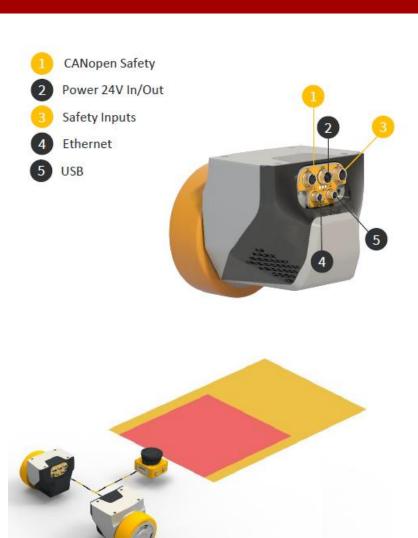


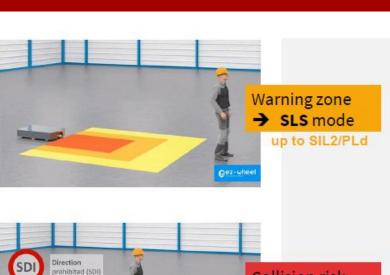
AMR configurator

Mobile robot configuration tool *To address integrators*

SWD® Integrated Safety











World's first integrated drives featuring Safe Motion & Safety Encoder



SWD® - World's first Safety Wheel Drive



World's first wheel drive

- with embedded Safe Motion
- with integrated safety encoder
- with chainable safety bus

SIL2 / PLd / Cat.3 SIL3 / PLe / Cat.4

AGV safety compliance

Fulfills most complex 3691-4 safety requirements :

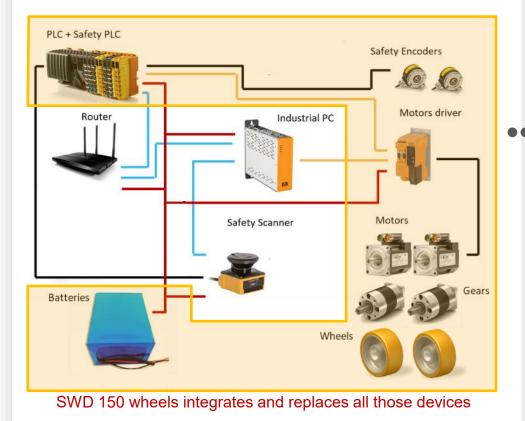
- → speeds limits according to safe detection areas
- → machine maximum absolute speed configuration
- → Stop & brake control



SWD® - Simpler Integration & Lower Cost



Typical solution for AMR development



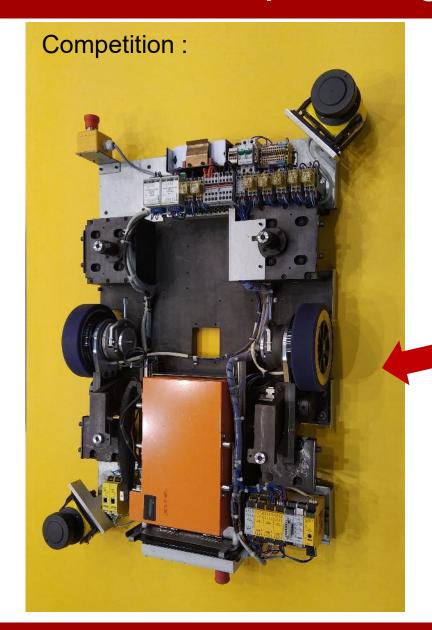


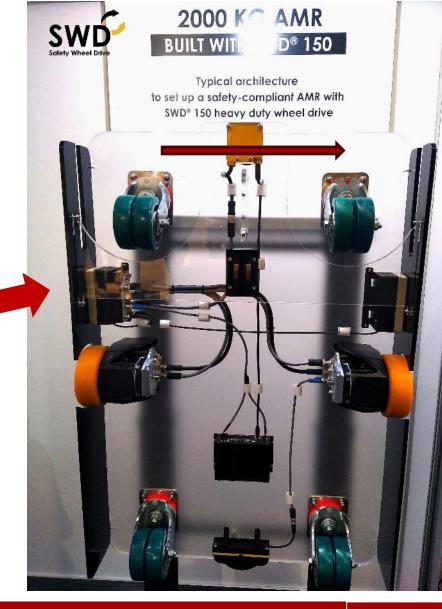
- **❖ Very simple** integration
- Full embedded safety
- Low energy consumption
- Hardware cost down

SWD® - Simpler Integration & Lower Cost

VS.







SWD® - EW2A range



EW2A-000xxxx Safety Gear moto



EW2A-125xxxx Safety wheel drive



EW2A-150xxxxSafety wheel drive



Nominal performance	185 W (S1)	200 W (S1)	185 W (S1)
Speed	0 – 130 RPM	0 to 11 km/h	0 to 3,7 km/h
Max. vertical load	-	Up to 250 kg	Up to 700 kg
Wheel diameter	-	125 mm	150 mm
Type of tyre	-	PU 80 sh. A – Flat profile	PU 92 sh. A – Flat profile
Pushing effort	37 Nm	20 daN / 500 kg moved	60 daN / 1.5T moved
Option(s)	Parking Brake /B		Parking Brake /B Internal battery (100 Wh)

Note: Values for standard gear ratios. See online datasheets for variants

SWD® Starter Kit - Safety ready, ROS dev platform



Development platform to experiment SWD® products

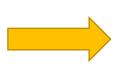
All developments done on the Starter Kit can be transferred seamlessly to any product of the SWD® range

The portability is ensured to the SWD® wheels with or w/o integrated batteries



SWD® Starter Kit Versatile and open development platform

























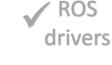






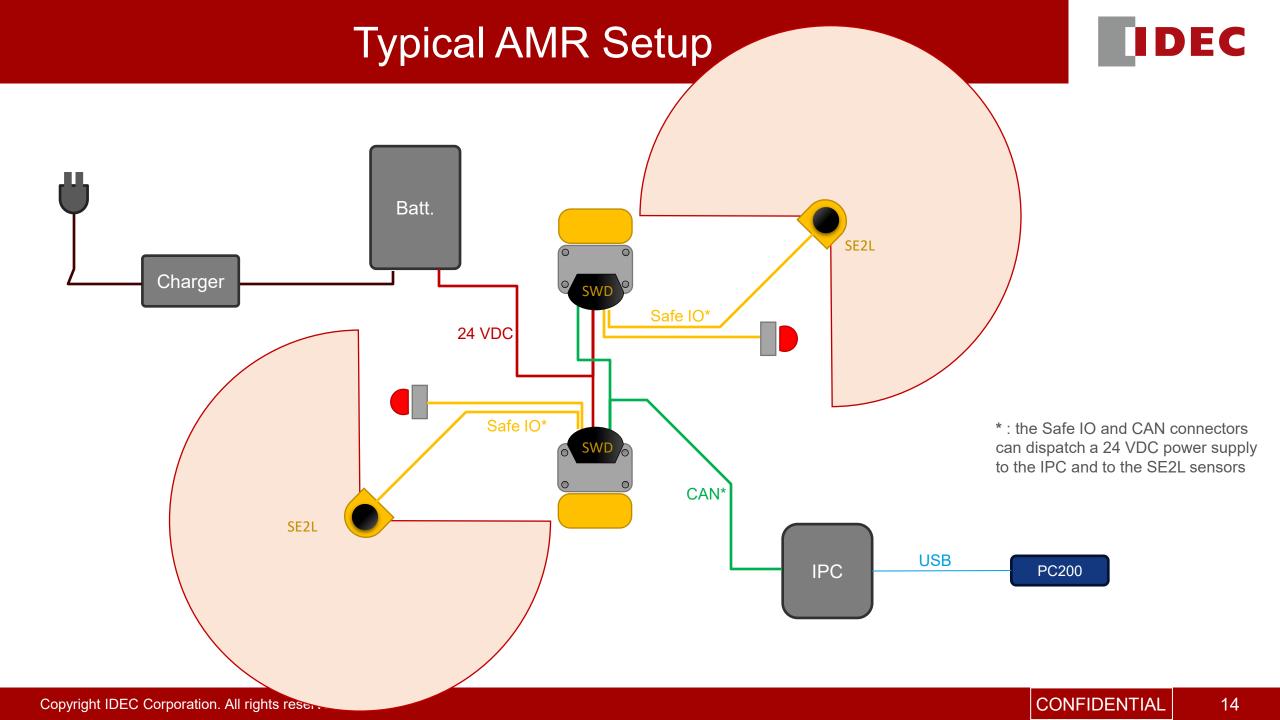






drivers





Cobot mode



- ROS driver
 - Available for ROS and ROS2
- swd_diff_drive_controller node
 - /cmd vel : Target linear and angular velocities
 - /set speed : Target speeds in rad/s for left and right wheels.
 - /odom : Odometry message based on wheels encoders
- https://github.com/ezWheelSAS/swd_ros2_controllers

ez-Way® - Software suite for Robots control



3rd party fleet management (server)

- Available from multiple players
- Compliant with VDA 5050
- Suitable for heterogeneous fleets of AGVs

Cloud & Messaging

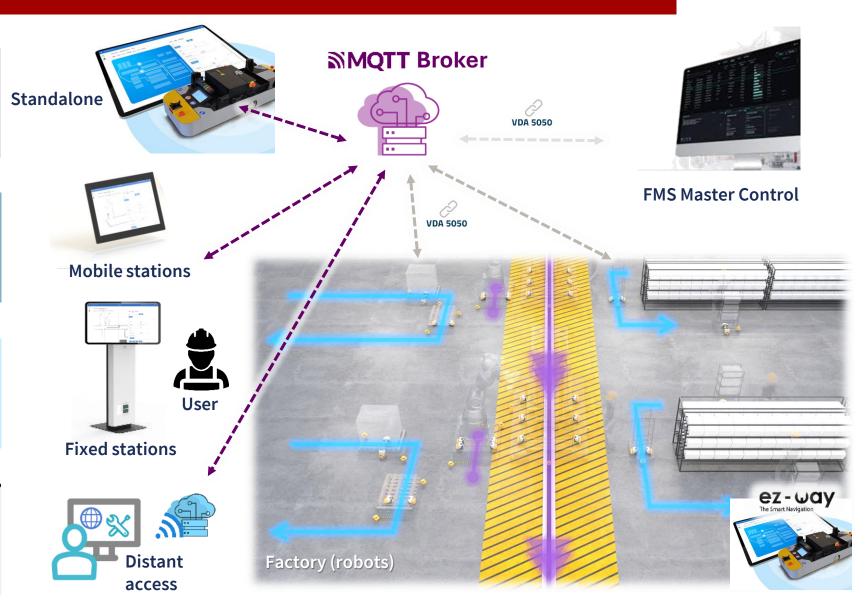
- MQTT messaging based on VDA 5050 standard
- Global access & multi-users management
- Full Cloud & SaaS offers available

ez-Way navigation & control (robots)

- Hardware management (control & monitoring)
- Localization & sensors management
- Navigation (guided, path following)

Maintenance (Local / Distant)

- Distant access for diagnostics and support
- Software updates
- Diagnostic page accessible



ez-Way® – Controllable from 3rd party FMS



ez-Way

Through ez-Way's **"VDA 5050 interface"**, mobile robots can be controlled by any 3rd party Fleet Management System.





3rd party fleet management (server)

- Available from multiple players
- Compliant with VDA 5050
- Suitable for heterogeneous fleets of AGVs



KINEXON

idealııjorks

SYNAOS

Network & Messaging

- MQTT messaging based on VDA 5050 standard
- Global access & multi-users management
- Full Cloud & SaaS offers available

MQTT



ez-Way navigation & control (robots)

- Hardware management (control & monitoring)
- Localization & sensors management
- Navigation (guided, path following)



NB: FMS suppliers names are given as examples; compatibility is not tested.

IDEC

STARTER KIT

ez-Way[®] Local – Custom Actions



In ez-Way Control Page "Custom Actions" can be triggered on a "node" during the mission, to execute customer specific tasks.

- Executed by the embedded IPC running ez-Way
- Executed by a 3rd party PLC, through a Modbus TCP bridge

MQTT Broker





Examples:

- FMS
- Customer PLC
- Automatic system

VDA 5050



- · Wait for external trigger
- New mission
- Customer specific program (ROS, Python, C++)

• ...

Modbus



IPC running ez-Way



Examples:

Turn on light
Engage action on AGV top

...

Custom Action

- Affect a specific mission
- Engage an actuator (conveyor, lift, pin...)
- Execute an action on a 3rd party PLC
- Wait for a specific traffic rule



Node as per VDA 5050

ez-Way® local - Navigation modes



Map-based navigation

- Virtual line following navigation
- SLAM based localization
- Using data from safety LiDAR(s)
- Path defined in the FMS

Line following navigation

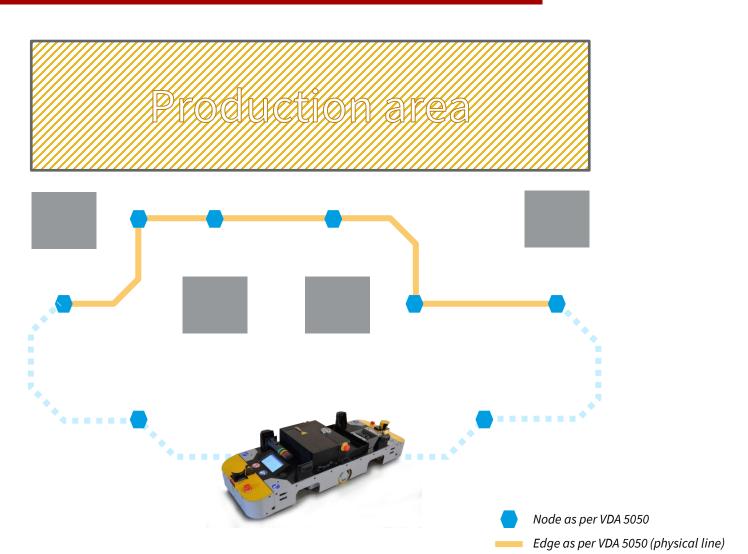
- Physical line following navigation
- Magnetic or optical line-based localization
- Using data from dedicated sensor
- Path defined by the infrastructure



Combined-modes navigation

- Virtual / Physical line following
- Can be selected for each path
- Seamless multi-sensor integration
- Path defined in the FMS





Edge as per VDA 5050 (virtual line)





Thank you for listening!